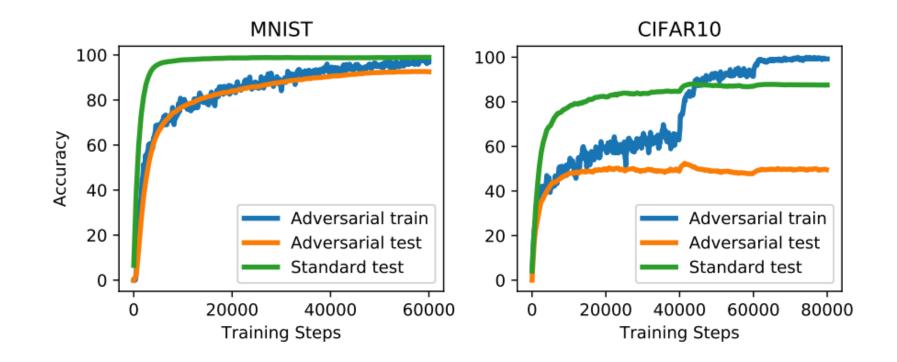
# Rethinking Softmax Cross-Entropy Loss for Adversarial Robustness

(ICLR 2020)

Tianyu Pang, Kun Xu, Yinpeng Dong, Chao Du, Ning Chen and Jun Zhu

#### **Motivation**



The same dataset, e.g., CIFAR-10, which enables good standard accuracy may not suffice to train robust models.

(Schmidt et al. NeurIPS 2018)

#### **Possible Solutions**

# Introducing extra labeled data

(Hendrycks et al. ICML 2019)

# Introducing extra unlabeled data

(Alayrac et al. NeurIPS 2019; Carmon et al. NeurIPS 2019)

#### **Possible Solutions**

## Introducing extra labeled data

(Hendrycks et al. ICML 2019)

# • Introducing extra unlabeled data

(Alayrac et al. NeurIPS 2019; Carmon et al. NeurIPS 2019)

• Our solution: Increase sample density to induce locally sufficient training data for robust learning

#### **Possible Solutions**

# Introducing extra labeled data

(Hendrycks et al. ICML 2019)

# • Introducing extra unlabeled data

(Alayrac et al. NeurIPS 2019; Carmon et al. NeurIPS 2019)

• Our solution: Increase sample density to induce locally sufficient training data for robust learning

**Q1: What is the definition of sample density?** 

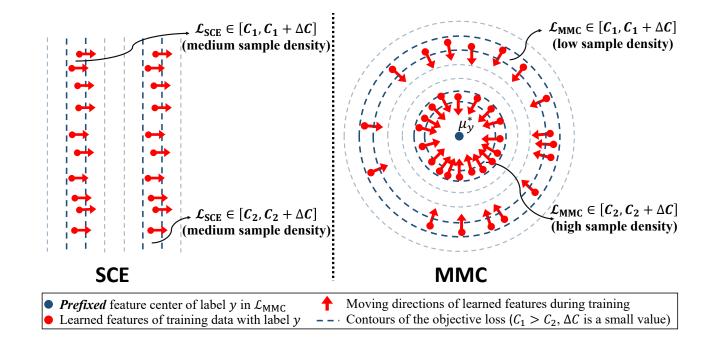
Q2: Can existing training objectives induce high sample density?

#### **Sample Density**

Given a training dataset  $\mathcal{D}$  with N input-label pairs, and the feature mapping Z trained by the objective  $\mathcal{L}(Z(x), y)$  on this dataset, we define the sample density nearby the feature point z = Z(x) following the similar definition in physics (Jackson, 1999) as

$$\mathbb{SD}(z) = \frac{\Delta N}{\operatorname{Vol}(\Delta B)}.$$
(2)

Here  $Vol(\cdot)$  denotes the volume of the input set,  $\Delta B$  is a small neighbourhood containing the feature point z, and  $\Delta N = |Z(\mathcal{D}) \cap \Delta B|$  is the number of training points in  $\Delta B$ , where  $Z(\mathcal{D})$  is the set of all mapped features for the inputs in  $\mathcal{D}$ . Note that the mapped feature z is still of the label y.



#### **Generalized Softmax Cross Entropy Loss (g-SCE loss)**

We define g-SCE loss as

$$\mathcal{L}_{g-SCE}(Z(x), y) = -1_y^+ \log [\operatorname{softmax}(h)],$$
  
where  $h_i = -(z - \mu_i)^\top \Sigma_i (z - \mu_i) + B_i$  is the logits in quadratic form.

#### **Generalized Softmax Cross Entropy Loss (g-SCE loss)**

We define g-SCE loss as

$$\mathcal{L}_{g ext{-SCE}}(Z(x),y) = -1_y^ op \log [ ext{softmax}(h)],$$
  
where  $h_i = -(z - \mu_i)^ op \Sigma_i (z - \mu_i) + B_i$  is the logits in quadratic form.

#### We note that the SCE loss is included in the family of g-SCE loss as

$$\operatorname{softmax}(Wz+b)_{i} = \frac{\exp(W_{i}^{\top}z+b_{i})}{\sum_{l\in[L]}\exp(W_{l}^{\top}z+b_{l})} = \frac{\exp(-\|z-\frac{1}{2}W_{i}\|_{2}^{2}+b_{i}+\frac{1}{4}\|W_{i}\|_{2}^{2})}{\sum_{l\in[L]}\exp(-\|z-\frac{1}{2}W_{l}\|_{2}^{2}+b_{l}+\frac{1}{4}\|W_{l}\|_{2}^{2})}$$

To provide a formal representation of the sample density induced by the g-SCE loss, we first derive the formula of the contours

$$\mathcal{L}_{g\text{-SCE}}(Z(x), y) = C$$

To provide a formal representation of the sample density induced by the g-SCE loss, we first derive the formula of the contours

$$\mathcal{L}_{g\text{-SCE}}(Z(x), y) = C$$

$$\bigcup$$

$$\log\left(1 + \frac{\sum_{l \neq y} \exp(h_l)}{\exp(h_y)}\right) = C \implies h_y = \log\left[\sum_{l \neq y} \exp(h_l)\right] - \log(C_e - 1).$$

To provide a formal representation of the sample density induced by the g-SCE loss, we first derive the formula of the contours

$$\mathcal{L}_{g\text{-SCE}}(Z(x), y) = C$$

$$\log\left(1 + \frac{\sum_{l \neq y} \exp(h_l)}{\exp(h_y)}\right) = C \implies h_y = \log\left[\sum_{l \neq y} \exp(h_l)\right] - \log(C_e - 1).$$

Log-Sum-Exp function, which is a soft maximum function

To provide a formal representation of the sample density induced by the g-SCE loss, we first derive the formula of the contours

 $\mathcal{L}_{\sigma-SCE}(Z(x), y) = C$  $\log\left(1 + \frac{\sum_{l \neq y} \exp(h_l)}{\exp(h_y)}\right) = C \implies h_y = \log\left[\sum_{l \neq y} \exp(h_l)\right] - \log(C_e - 1).$ approximately  $h_u - h_{\tilde{u}} = -\log(C_e - 1),$ 

where  $C_e = \exp(C)$ , and  $\tilde{y} = \arg \max_{l \neq y} h_l$ .

We can the approximate loss as

$$\mathcal{L}_{y,\tilde{y}}(z) = \log[\exp(h_{\tilde{y}} - h_y) + 1]$$

such that

#### **The Neighborhood** △*B* **in Sample Density**

Based on the above approximation, we can now approximate the neighborhood

$$\Delta B = \{ \mathbf{z} \in \mathbb{R}^d | \mathcal{L}(\mathbf{z}, y) \in [C, C + \Delta C] \}$$

approximately

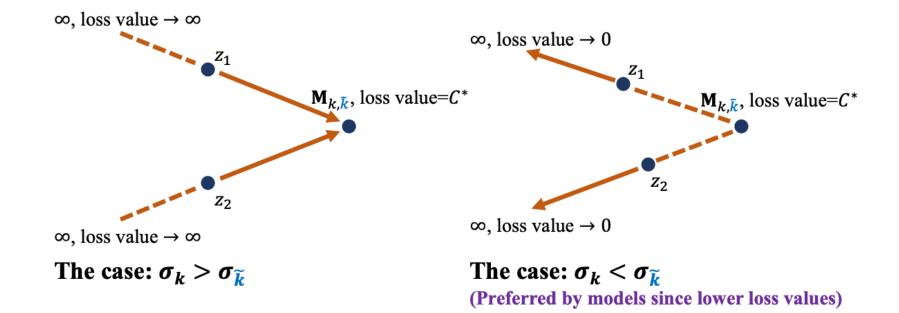
$$\Delta B_{y,\tilde{\mathbf{y}}} = \{ \mathbf{z} \in \mathbb{R}^d | \mathcal{L}_{y,\tilde{\mathbf{y}}}(\mathbf{z}) \in [C, C + \Delta C] \}$$

#### **Induced Sample Density of g-SCE Loss**

**Theorem 1.** (Proof in Appendix A.1) Given  $(x, y) \in \mathcal{D}_{k,\tilde{k}}$ , z = Z(x) and  $\mathcal{L}_{g-SCE}(z, y) = C$ , if there are  $\Sigma_k = \sigma_k I$ ,  $\Sigma_{\tilde{k}} = \sigma_{\tilde{k}} I$ , and  $\sigma_k \neq \sigma_{\tilde{k}}$ , then the sample density nearby the feature point z based on the approximation in Eq. (6) is

$$\mathbb{SD}(z) \propto \frac{N_{k,\tilde{k}} \cdot p_{k,\tilde{k}}(C)}{\left[\mathbf{B}_{k,\tilde{k}} + \frac{\log(C_e - 1)}{\sigma_k - \sigma_{\tilde{k}}}\right]^{\frac{d-1}{2}}}, and \ \mathbf{B}_{k,\tilde{k}} = \frac{\sigma_k \sigma_{\tilde{k}} \|\mu_k - \mu_{\tilde{k}}\|_2^2}{(\sigma_k - \sigma_{\tilde{k}})^2} + \frac{B_k - B_{\tilde{k}}}{\sigma_k - \sigma_{\tilde{k}}}, \tag{7}$$

where for the input-label pair in  $\mathcal{D}_{k,\tilde{k}}$ , there is  $\mathcal{L}_{g-SCE} \sim p_{k,\tilde{k}}(c)$ .



#### **The 'Curse' of Softmax Function**

$$\mathcal{L}_{g\text{-SCE}}(Z(x), y) = -\mathbf{1}_{y}^{\top} \log [\operatorname{softmax}(h)],$$

- The softmax makes the loss value only depend on the relative relation among logits.
- This causes indirect and unexpected supervisory signals on the learned features.

#### **Our Method: Max-Mahalanobis Center (MMC) Loss**

$$\mathcal{L}_{\text{MMLDA}}(Z(x), y) = -\log\left[\frac{\exp(-\frac{\|z-\mu_y^*\|_2^2}{2})}{\sum_{l\in[L]}\exp(-\frac{\|z-\mu_l^*\|_2^2}{2})}\right] = -\log\left[\frac{\exp(z^\top \mu_y^*)}{\sum_{l\in[L]}\exp(z^\top \mu_l^*)}\right]$$

#### **Our Method: Max-Mahalanobis Center (MMC) Loss**

$$\mathcal{L}_{\text{MMLDA}}(Z(x), y) = \log \left[ \frac{\exp(-\frac{\|z-\mu_y^*\|_2^2}{2})}{\sum_{l \in [L]} \exp(-\frac{\|z-\mu_l^*\|_2^2}{2})} \right] = -\log \left[ \frac{\exp(z^\top \mu_y^*)}{\sum_{l \in [L]} \exp(z^\top \mu_l^*)} \right]$$
$$\mathcal{L}_{\text{MMC}}(Z(x), y) = \frac{1}{2} \|z - \mu_y^*\|_2^2$$

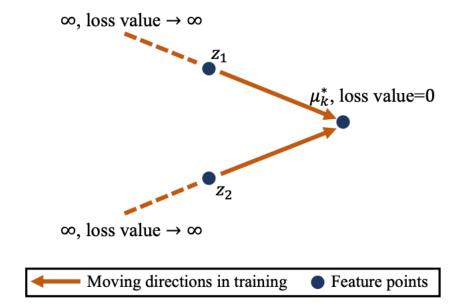
• No softmax normalization

#### **Induced Sample Density of MMC Loss**

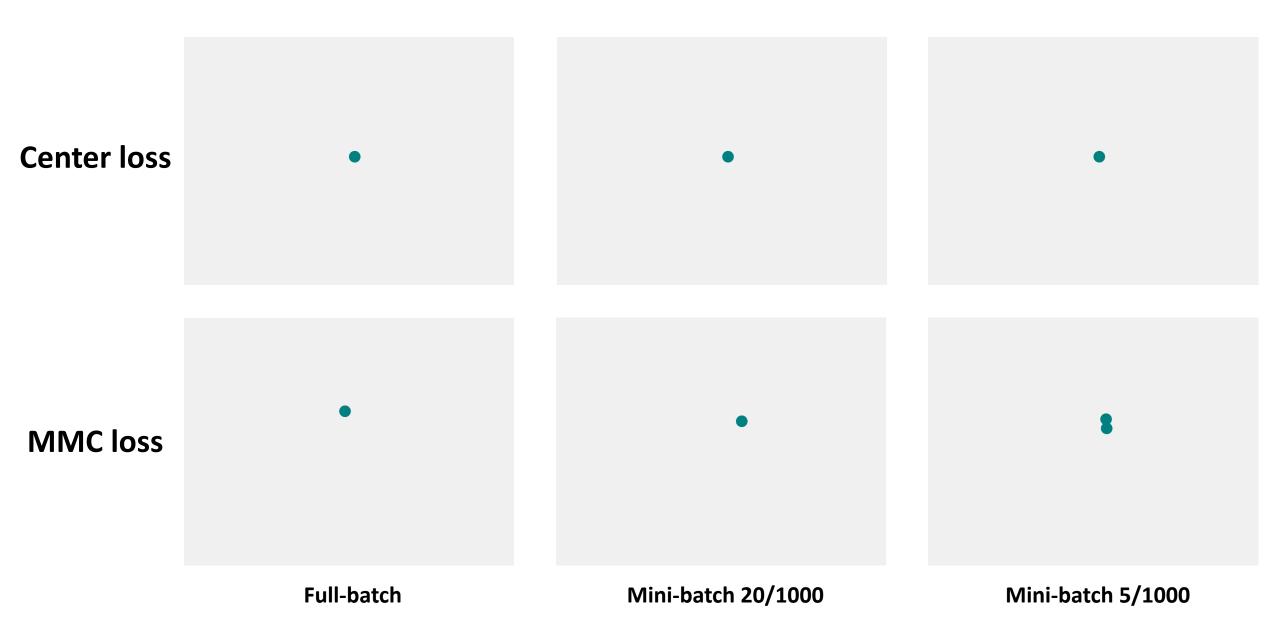
**Theorem 2.** (Proof in Appendix A.2) Given  $(x, y) \in D_k$ , z = Z(x) and  $\mathcal{L}_{MMC}(z, y) = C$ , the sample density nearby the feature point z is

$$\mathbb{SD}(z) \propto \frac{N_k \cdot p_k(C)}{C^{\frac{d-1}{2}}},\tag{9}$$

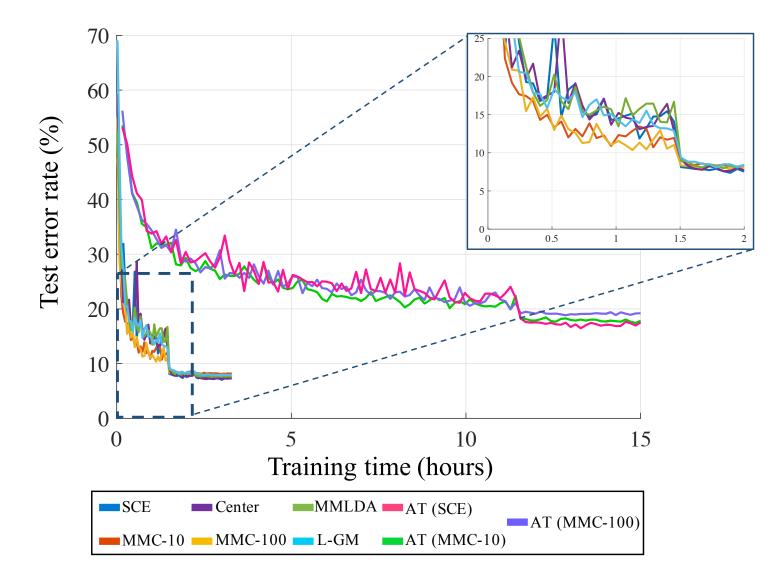
where for the input-label pair in  $\mathcal{D}_k$ , there is  $\mathcal{L}_{MMC} \sim p_k(c)$ .



# **Toy Demo on Faster Convergence**



# **Empirical Faster Convergence**

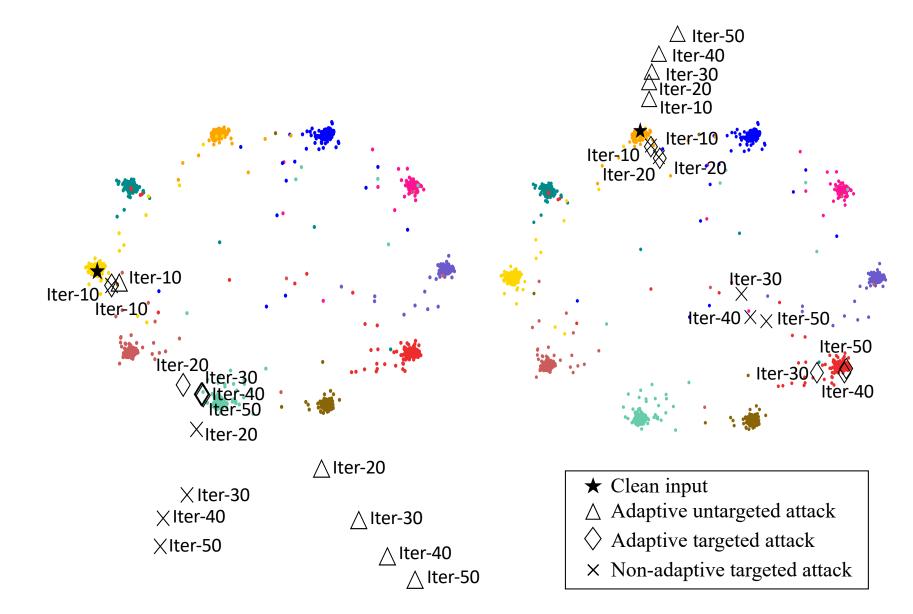


# White-box Robustness (Adaptive Attacks)

		<b>Perturbation</b> $\epsilon = 8/255$				<b>Perturbation</b> $\epsilon = 16/255$				
Methods	Clean	PGD <sub>10</sub> <sup>tar</sup>	PGD <sub>10</sub> <sup>un</sup>	PGD <sub>50</sub> <sup>tar</sup>	PGD <sub>50</sub> <sup>un</sup>	$\mathbf{PGD}_{10}^{\mathbf{tar}}$	PGD <sub>10</sub> <sup>un</sup>	PGD <sub>50</sub> <sup>tar</sup>	PGD <sub>50</sub> <sup>un</sup>	
SCE	92.9	$\leq 1$	3.7	$\leq 1$	3.6	$\leq 1$	2.9	$\leq 1$	2.6	
Center loss	92.8	$\leq 1$	4.4	$\leq 1$	4.3	$\leq 1$	3.1	$\leq 1$	2.9	
MMLDA	92.4	$\leq 1$	16.5	$\leq 1$	9.7	$\leq 1$	6.7	$\leq 1$	5.5	
L-GM	92.5	37.6	19.8	8.9	4.9	26.0	11.0	2.5	2.8	
MMC-10 (rand)	92.3	43.5	29.2	20.9	18.4	31.3	17.9	8.6	11.6	
<b>MMC-10</b>	92.7	48.7	36.0	26.6	24.8	36.1	25.2	13.4	17.5	
AT <sub>10</sub> <sup>tar</sup> (SCE)	83.7	70.6	49.7	69.8	47.8	48.4	26.7	31.2	16.0	
$AT_{10}^{tar} (MMC-10)$	83.0	69.2	54.8	67.0	53.5	58.6	47.3	44.7	45.1	
AT <sup>un</sup> <sub>10</sub> (SCE)	80.9	69.8	55.4	69.4	53.9	53.3	34.1	38.5	21.5	
AT <sup>un</sup> <sub>10</sub> (MMC-10)	81.8	70.8	56.3	70.1	55.0	54.7	37.4	39.9	27.7	

#### CIFAR-10

#### White-box Robustness (Adaptive Attacks)

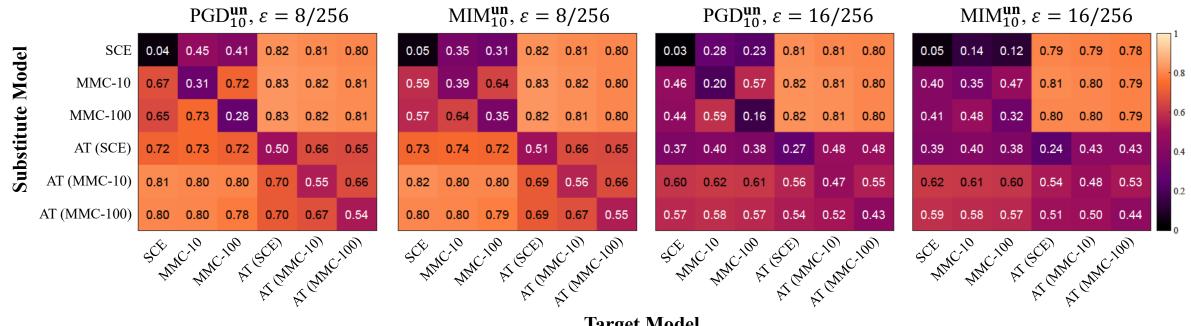


## White-box Robustness (Adaptive Attacks)

	Part I		<b>Part II</b> ( $\epsilon = 8/255$ )		<b>Part II</b> ( $\epsilon = 16/255$ )		Part III	
Methods	C&W <sup>tar</sup>	C&W <sup>un</sup>	$\mathbf{SPSA}_{10}^{\mathbf{tar}}$	SPSA <sup>un</sup> <sub>10</sub>	$SPSA_{10}^{tar}$	SPSA <sup>un</sup> <sub>10</sub>	Noise	Rotation
SCE	0.12	0.07	12.3	1.2	5.1	$\leq 1$	52.0	83.5
Center loss	0.13	0.07	21.2	6.0	10.6	2.0	55.4	84.9
MMLDA	0.17	0.10	25.6	13.2	11.3	5.7	57.9	84.8
L-GM	0.23	0.12	61.9	45.9	46.1	28.2	59.2	82.4
MMC-10	0.34	0.17	69.5	56.9	57.2	41.5	69.3	87.2
AT <sub>10</sub> <sup>tar</sup> (SCE)	1.19	0.63	81.1	67.8	77.9	59.4	82.2	76.0
AT <sub>10</sub> <sup>tar</sup> (MMC-10)	1.91	0.85	79.1	69.2	74.5	62.7	83.5	75.2
AT <sub>10</sub> <sup>un</sup> (SCE)	1.26	0.68	78.8	67.0	73.7	60.3	78.9	73.7
AT <sup>un</sup> <sub>10</sub> (MMC-10)	1.55	0.73	80.4	69.6	74.6	62.4	80.3	75.8

#### CIFAR-10

#### **Black-box Robustness (Exclude Gradient Masking)**



**Target Model** 

#### **Different Architectures**

		<b>Perturbation</b> $\epsilon = 8/255$				<b>Perturbation</b> $\epsilon = 16/255$				
Methods	Cle.	PGD <sub>10</sub> <sup>tar</sup>	PGD <sub>10</sub> <sup>un</sup>	PGD <sub>50</sub> <sup>tar</sup>	PGD <sub>50</sub> <sup>un</sup>	PGD <sub>10</sub> <sup>tar</sup>	$PGD_{10}^{un}$	PGD <sub>50</sub> <sup>tar</sup>	PGD <sub>50</sub>	
CIFAR-10										
SCE (Res.32)	93.6	$\leq 1$	3.7	$\leq 1$	3.6	$\leq 1$	2.7	$\leq 1$	2.9	
MMC (Res.32)	92.7	48.7	36.0	26.6	24.8	36.1	25.2	13.4	17.5	
SCE (Res.110)	94.7	$\leq 1$	3.0	$\leq 1$	2.9	$\leq 1$	2.1	$\leq 1$	2.0	
MMC (Res.110)	93.6	54.7	46.0	34.4	31.4	41.0	30.7	16.2	21.6	
CIFAR-100										
SCE (Res.32)	72.3	$\leq 1$	7.8	$\leq 1$	7.4	$\leq 1$	4.8	$\leq 1$	4.7	
MMC (Res.32)	71.9	23.9	23.4	15.1	21.9	16.4	16.7	8.0	15.7	
SCE (Res.110)	74.8	$\leq 1$	7.5	$\leq 1$	7.3	$\leq 1$	4.7	$\leq 1$	4.5	
MMC (Res.110)	73.2	34.6	22.4	23.7	16.5	24.1	14.9	13.9	10.5	

# Thanks