



## Two Birds with One Stone: Series Saliency for Accurate and Interpretable Multivariate Time Series Forecasting

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## Introduction

□ It is important yet challenging to perform accurate and interpretable time series forecasting. Traditional parametric model are easy-to-interpret, but their predictive capabilities are limited. Deep architectures can boost the forecasting accuracy, they sacrifice interpretability. It is relatively unexplored to develop both accurate and interpretable methods for multivariate time series forecasting.

### **Existing work:**

1. Interpretation methods for general neural networks [Ribeiro et al., 2016; Shrikumar et al., 2017; Lundberg & Lee 2017]:

Use gradient information to extract feature information for after the back- propagation

2. Transfer attention methods from the fields of language or vision [Bahadanau et al., 2014, Shih et al., 2019]:

Attention values are calculated via the relative importance of the different time steps.

### □ Key: Considering the time and feature dimensions in **coherent** manner

- Represent the multivariate time series as a set of *window* × *feature* 2D series images.
- Each series image corresponds to a part of the multivariate time series within a given time window.
- Each row corresponds to one feature dimension.
- Window Multivariate Time Series **Temporal Saliency Map**
- Follow the perturbation strategy in the smallest destroying region (SDR) principle [Dabkowski & Gal, 2017] for the reference series image.

$$\hat{x}_{t,i} = \begin{cases} x_{t,i} + \epsilon_{\sigma_1} & \text{noise} \\ g_{\sigma_2}(x_{t,i}) & \text{blur} \end{cases}$$

- Each series can be composed of three parts: trend, seasonality and residual [Hyandman & Athanasopoulos, 2018]
- Adding Gaussian blur extracts the trend information, and adding some noise enhances local information.

### **Motivation:** Sensitivity over perturbation for DNNs in time domain

- When the amount of injected noise or blurring is small, the reference series image can be treated as data augmentation in time domain for deep models.
- If the perturbation is not set properly (e.g., too large), the blurring will introduce irregular roughness to cover the original series, making it difficult for DNNs to learn temporal patterns.

Series saliency module  $[0,1]^{D \times T}$  and selectively combines the reference series images and original one:

Series saliency can generate data that cover the unexplored important characteristics of the original series image.

### **Dual-path architecture**

a non-periodic manner

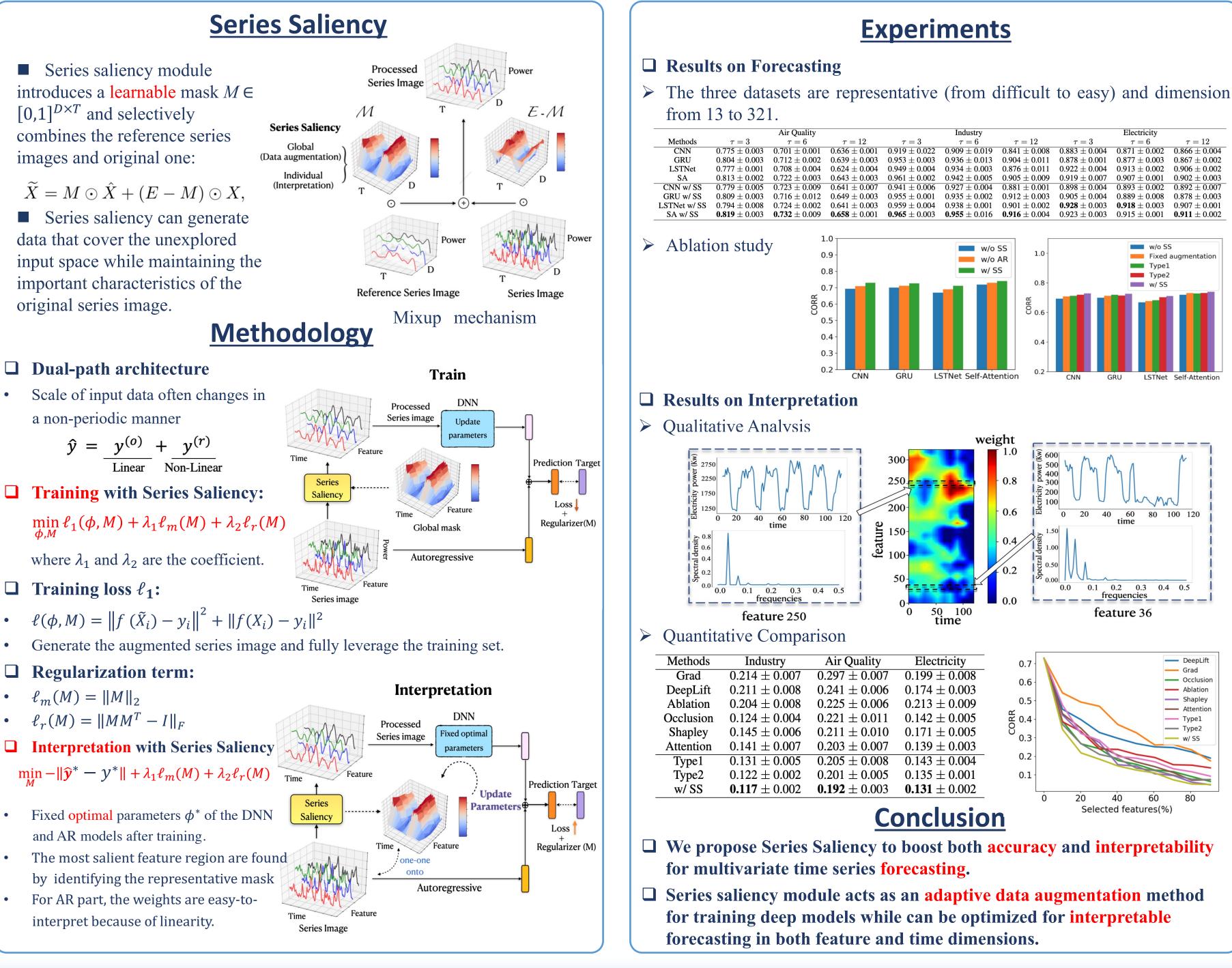
$$= y^{(a)}$$

- **Training loss**  $\ell_1$ :

- **Regularization term:**
- $\ell_m(M) = \|M\|_2$
- $\ell_r(M) = \|MM^T I\|_F$

- and AR models after training.
- interpret because of linearity.

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Industry		Electricity
au=6	$\tau = 12$	au = 3 $ au = 6$ $ au = 12$
$0.909 \pm 0.019$ $0.936 \pm 0.013$	$\begin{array}{c} 0.841 \pm 0.008 \\ 0.904 \pm 0.011 \end{array}$	$\begin{array}{c} 0.883 \pm 0.004 & 0.871 \pm 0.002 & 0.866 \pm 0.004 \\ 0.878 \pm 0.001 & 0.877 \pm 0.003 & 0.867 \pm 0.002 \end{array}$
$0.934 \pm 0.003$	$0.876\pm0.011$	$0.922 \pm 0.004  0.913 \pm 0.002  0.906 \pm 0.002$
$\frac{0.942 \pm 0.005}{0.927 \pm 0.004}$	$\frac{0.905 \pm 0.009}{0.881 \pm 0.001}$	$\begin{array}{c} 0.919 \pm 0.007 & 0.907 \pm 0.001 & 0.902 \pm 0.003 \\ \hline 0.898 \pm 0.004 & 0.893 \pm 0.002 & 0.892 \pm 0.007 \end{array}$
$0.927 \pm 0.004$ $0.935 \pm 0.002$	$0.881 \pm 0.001$ $0.912 \pm 0.003$	$\begin{array}{c} 0.898 \pm 0.004 & 0.893 \pm 0.002 & 0.892 \pm 0.007 \\ 0.905 \pm 0.004 & 0.889 \pm 0.008 & 0.878 \pm 0.003 \end{array}$
$0.938 \pm 0.001$	$0.901 \pm 0.002$	$0.928 \pm 0.003  0.918 \pm 0.003  0.907 \pm 0.001 \\ 0.022 \pm 0.002  0.015 \pm 0.001  0.001 \pm 0.001$
<b>0.955</b> ± 0.016	$0.916 \pm 0.004$	$0.923 \pm 0.003  0.915 \pm 0.001  0.911 \pm 0.002$
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